## Chapter 3



## Boolean Algebra and Digital Logic

## Objectives

- Understand the relationship between Boolean logic and digital computer circuits.
- Learn how to design simple logic circuits.
- Understand how digital circuits work together to form complex computer systems.


### 3.1 Introduction (1 of 2)

- In the latter part of the nineteenth century, George Boole incensed philosophers and mathematicians alike when he suggested that logical thought could be represented through mathematical equations.
- How dare anyone suggest that human thought could be encapsulated and manipulated like an algebraic formula?
- Computers, as we know them today, are implementations of Boole's Laws of Thought.
- John Atanasoff and Claude Shannon were among the first to see this connection.


### 3.1 Introduction (2 of 2)

- In the middle of the twentieth century, computers were commonly known as "thinking machines" and "electronic brains."
- Many people were fearful of them.
- Nowadays, we rarely ponder the relationship between electronic digital computers and human logic. Computers are accepted as part of our lives.
- Many people, however, are still fearful of them.
- In this chapter, you will learn the simplicity that constitutes the essence of the machine.


### 3.2 Boolean Algebra (1 of 17)

- Boolean algebra is a mathematical system for the manipulation of variables that can have one of two values.
- In formal logic, these values are "true" and "false."
- In digital systems, these values are "on" and "off," 1 and 0, or "high" and "low."
- Boolean expressions are created by performing operations on Boolean variables.
- Common Boolean operators include AND, OR, and NOT.


### 3.2 Boolean Algebra (2 of 17)

- A Boolean operator can be completely described using a truth table.
- The truth table for the Boolean operators AND and OR are shown at the right.
- The AND operator is also known as a Boolean product. The OR operator is the Boolean sum.

| X |  | AND Y |
| :---: | :---: | :---: |
| X | Y | XY |
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |


| X OR Y |  |  |
| :---: | :---: | :---: |
| X | Y | $\mathrm{X}+\mathrm{Y}$ |
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |

### 3.2 Boolean Algebra (3 of 17)

- The truth table for the

Boolean NOT operator is shown at the right.

- The NOT operation is most often designated by a prime mark ( $\mathbf{X}^{\prime}$ ). It is sometimes

NOT $x$
 indicated by an overbar ( $\overline{\mathbf{X}}$ ) or an "elbow" ( $\neg \mathbf{x}$ ).

### 3.2 Boolean Algebra (4 of 17)

- A Boolean function has:
- at least one Boolean variable,
- at least one Boolean operator, and
- at least one input from the set $\{0,1\}$.
- It produces an output that is also a member of the set $\{0,1\}$.
Now you know why the binary numbering system is so handy in digital systems.


### 3.2 Boolean Algebra (5 of 17)

- The truth table for the Boolean function:

$$
F(x, y, z)=x z^{\prime}+y
$$

is shown at the right.

- To make evaluation of the Boolean function easier, the
$F(x, y, z)=x z^{\prime}+y$

| $x$ | $y$ | $z$ | $z^{\prime}$ | $x z^{\prime}$ | $x z^{\prime}+y$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 |
| 1 | 1 | 1 | 0 | 0 | 1 | truth table contains extra (shaded) columns to hold evaluations of subparts of the function.

### 3.2 Boolean Algebra (6 of 17)

- As with common arithmetic, Boolean operations have rules of precedence.
- The NOT operator has highest priority, followed by AND and then OR.
$F(x, y, z)=x z^{\prime}+y$

| $x$ | $y$ | $z$ | $z$ | $x z^{\prime}$ | $x z^{\prime}+y$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 1 | 0 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 |
| 0 | 1 | 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 0 | 0 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 |
| 1 | 1 | 1 | 0 | 0 | 1 |

- This is how we chose the (shaded) function subparts in our table.


### 3.2 Boolean Algebra (7 of 17)

- Digital computers contain circuits that implement Boolean functions.
- The simpler that we can make a Boolean function, the smaller the circuit that will result.
- Simpler circuits are cheaper to build, consume less power, and run faster than complex circuits.
- With this in mind, we always want to reduce our Boolean functions to their simplest form.
- There are a number of Boolean identities that help us to do this.


### 3.2 Boolean Algebra (8 of 17)

- Most Boolean identities have an AND (product) form as well as an OR (sum) form. We give our identities using both forms. Our first group is rather intuitive:

| Identity <br> Name | AND <br> Form | OR <br> Form |
| :--- | :---: | :---: |
| Identity Law | $1 \mathbf{x}=\mathbf{x}$ | $0+\mathbf{x}=\mathbf{x}$ |
| Null Law | $0 x=0$ | $1+\mathbf{x}=1$ |
| Idempotent Law | $\mathbf{x x}=\mathbf{x}$ | $\mathbf{x}+\mathbf{x}=\mathbf{x}$ |
| Inverse Law | $\mathbf{x x '}=0$ | $\mathbf{x + x}=1$ |

### 3.2 Boolean Algebra (9 of 17)

- Our second group of Boolean identities should be familiar to you from your study of algebra:

| Identity | AND |  |
| :---: | :---: | :---: |
| Name | Form | OR |
| Form |  |  |

### 3.2 Boolean Algebra (10 of 17)

- Our last group of Boolean identities are perhaps the most useful.
- If you have studied set theory or formal logic, these laws are also familiar to you.

| Identity <br> Name | AND <br> Form | OR <br> Form |
| :--- | :---: | :---: |
| Absorption Law <br> DeMorgan's Law | $x(x+y)=x$ <br> $(x y)^{\prime}=x^{\prime}+y^{\prime}$ | $x+x y=x$ <br> $(x+y)^{\prime}=x^{\prime} y^{\prime}$ |
| Double <br> Complement Law | $(x)^{\prime \prime}=x$ |  |

### 3.2 Boolean Algebra (11 of 17)

$$
F(x, y, z)=x y+x^{\prime} z+y z
$$

- We can use Boolean identities to simplify:

$$
\begin{aligned}
F(x, y, z) & =x y+x^{\prime} z+y z & & \\
& =x y+x^{\prime} z+y z(1) & & \text { (Identity) } \\
& =x y+x^{\prime} z+y z\left(x+x^{\prime}\right) & & \text { (Inverse) } \\
& =x y+x^{\prime} z+(y z) x+(y z) x^{\prime} & & \text { (Distributive) } \\
& =x y+x^{\prime} z+x(y z)+x^{\prime}(z y) & & \text { (Commutative) } \\
& =x y+x^{\prime} z+(x y) z+\left(x^{\prime} z\right) y & & \text { (Associative twice) } \\
& =x y+(x y) z+x^{\prime} z+\left(x^{\prime} z\right) y & & \text { (Commutative) } \\
& =x y(1+z)+x^{\prime} z(1+y) & & \text { (Distributive) } \\
& =x y(1)+x^{\prime} z(1) & & \text { (Null) } \\
& =x y+x^{\prime} z & & \text { (Identity) }
\end{aligned}
$$

### 3.2 Boolean Algebra (12 of 17)

- Sometimes it is more economical to build a circuit using the complement of a function (and complementing its result) than it is to implement the function directly.
- DeMorgan's law provides an easy way of finding the complement of a Boolean function.
- Recall DeMorgan's law states:

$$
(x y)^{\prime}=x^{\prime}+y^{\prime} \text { and }(x+y)^{\prime}=x^{\prime} y^{\prime}
$$

### 3.2 Boolean Algebra (13 of 17)

- DeMorgan's law can be extended to any number of variables.
- Replace each variable by its complement and change all ANDs to ORs and all ORs to ANDs.
- Thus, we find the complement of:

$$
F(x, y, z)=(x y)+\left(x^{\prime} y\right)+\left(x z^{\prime}\right)
$$

is:

$$
\begin{aligned}
F^{\prime}(x, y, z) & =\left((x y)+\left(x^{\prime} y\right)+\left(x z^{\prime}\right)\right)^{\prime} \\
& =(x y){ }^{\prime}\left(x^{\prime} y\right){ }^{\prime}\left(x z^{\prime}\right)^{\prime} \\
& =\left(x^{\prime}+y^{\prime}\right)\left(x+y^{\prime}\right)\left(x^{\prime}+z\right)
\end{aligned}
$$

### 3.2 Boolean Algebra (14 of 17)

- Through our exercises in simplifying Boolean expressions, we see that there are numerous ways of stating the same Boolean expression.
- These "synonymous" forms are logically equivalent.
- Logically equivalent expressions have identical truth tables.
- In order to eliminate as much confusion as possible, designers express Boolean functions in standardized or canonical form.


### 3.2 Boolean Algebra (15 of 17)

- There are two canonical forms for Boolean expressions: sum-of-products and product-of-sums.
- Recall the Boolean product is the AND operation and the Boolean sum is the OR operation.
- In the sum-of-products form, ANDed variables are ORed together.
- For example: $F(X, Y, Z)=X Y+X Z+Y Z$
- In the product-of-sums form, ORed variables are ANDed together.
- For example:

$$
F(x, y, z)=(x+y)(x+z)(y+z)
$$

### 3.2 Boolean Algebra (16 of 17)

- It is easy to convert a function to sum-of-products form using its truth table.
- We are interested in the values of the variables that make the function true ( $=1$ ).
- Using the truth table, we list the values of the variables that result in a true function value.
$F(x, y, z)=x z^{\prime}+y$

| $x$ | $y$ | $z$ | $x z^{\prime}+y$ |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

- Each group of variables is then ORed together.


### 3.2 Boolean Algebra (17 of 17)

- The sum-of-products form for our function is:

$$
\begin{aligned}
F(x, y, z)= & \left(x x^{\prime} y z^{\prime}\right)+\left(x y^{\prime} y z\right) \\
& +\left(x y^{\prime} z^{\prime}\right)+(x y z ') \\
& +(x y z)
\end{aligned}
$$

$F(x, y, z)=x z^{\prime}+y$

| $x$ | $y$ | $z$ | $x z^{\prime}+y$ |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 1 |
| 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

We note that this function is not in simplest terms. Our aim is only to rewrite our function in canonical sum-of-products form.

### 3.3 Logic Gates (1 of 6)

- We have looked at Boolean functions in abstract terms.
- In this section, we see that Boolean functions are implemented in digital computer circuits called gates.
- A gate is an electronic device that produces a result based on two or more input values.
- In reality, gates consist of one to six transistors, but digital designers think of them as a single unit.
- Integrated circuits contain collections of gates suited to a particular purpose.


### 3.3 Logic Gates (2 of 6)

- The three simplest gates are the AND, OR, and NOT gates.

- They correspond directly to their respective Boolean operations, as you can see by their truth tables.


### 3.3 Logic Gates (3 of 6)

- Another very useful gate is the exclusive OR (XOR) gate.
- The output of the XOR operation is true only when the values of the inputs differ. X XOR Y

| $X$ | $Y$ | $X \oplus Y$ |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |



## Note the special symbol $\oplus$ for the XOR operation.

### 3.3 Logic Gates (4 of 6)

- NAND and NOR are two very important gates. Their symbols and truth tables are shown at the right.

| X NAND Y |  |  |
| :---: | :---: | :---: |
| X | Y | X NAND Y |
| 0 | 0 | 1 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 0 |
| X NOR Y |  |  |
| x | Y | X NOR Y |
| 0 | 0 | 1 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 0 |



### 3.3 Logic Gates (5 of 6)

- NAND and NOR are known as universal gates because they are inexpensive to manufacture and any Boolean function can be constructed using only NAND or only NOR gates.



### 3.3 Logic Gates (6 of 6)

- Gates can have multiple inputs and more than one output.
- A second output can be provided for the complement of the operation.
- We'll see more of this later.



### 3.4 Karnaugh Maps

- Simplification of Boolean functions leads to simpler (and usually faster) digital circuits.
- Simplifying Boolean functions using identities is time-consuming and errorprone.
- This special section presents an easy, systematic method for reducing Boolean expressions.


### 3.4.1 Introduction

- In 1953, Maurice Karnaugh was a telecommunications engineer at Bell Labs.
- While exploring the new field of digital logic and its application to the design of telephone circuits, he invented a graphical way of visualizing and then simplifying Boolean expressions.
- This graphical representation, now known as a Karnaugh map, or Kmap, is named in his honor.


### 3.4.2 Description of Kmaps and Terminology (1 of 5)

- A Kmap is a matrix consisting of rows and columns that represent the output values of a Boolean function.
- The output values placed in each cell are derived from the minterms of a Boolean function.
- A minterm is a product term that contains all of the function's variables exactly once, either complemented or not complemented.


### 3.4.2 Description of Kmaps and Terminology (2 of 5)

- For example, the minterms for a function having the inputs $x$ and $y$ are $\mathbf{x}^{\prime} \mathbf{y}, \mathbf{x}^{\prime} \mathbf{y}, \mathbf{x y}^{\prime}$, and $\mathbf{x y}$.

- Consider the Boolean function, $\mathbf{F}(\mathbf{x}, \mathbf{y})=\mathbf{x y}+\mathbf{x y}{ }^{\prime}$
- Its minterms are: $x y$ and $x y^{\prime}$


### 3.4.2 Description of Kmaps and Terminology (3 of 5)

- Similarly, a function having three inputs, has the minterms that are shown in this diagram.



### 3.4.2 Description of Kmaps and Terminology (4 of 5)

- A Kmap has a cell for each minterm.
- This means that it has a cell for each line for the truth table of a function.

| $F(X, Y)=X Y$ |  |  |
| :---: | :---: | :---: |
| $X$ | $Y$ | $X Y$ |
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |

- The truth table for the function $F(x, y)=x y$ is shown at the right along with its corresponding Kmap.

| Y | 0 | 1 |
| :---: | :---: | :---: |
| X | 0 | 1 |
| 0 | 0 | 0 |
| 1 | 0 | 1 |
|  |  |  |

### 3.4.2 Description of Kmaps and Terminology (5 of 5)

- As another example, we give the truth table and KMap for the function, $F(x, y)=x+y$ at the right.
- This function is equivalent to the OR of all of the minterms that have a value of 1. Thus:
$\mathrm{F}(\mathrm{x}, \mathrm{y})=\mathrm{x}+\mathrm{y}=\mathrm{x}^{\prime} \mathrm{y}+\mathrm{x} \mathrm{y}^{\prime}+\mathrm{xy}$

| $X$ | $Y$ | $X+Y$ |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |



### 3.4.3 Kmap Simplification for Two Variables (1 of 3)

- Of course, the minterm function that we derived from our Kmap was not in simplest terms.
- That's what we started with in this example.
- We can, however, reduce our complicated expression to its simplest terms by finding adjacent 1s in the Kmap that can be collected into groups that are powers of
 two.
- In our example, we have two such groups.
- Can you find them?


### 3.4.3 Kmap Simplification for Two Variables (2 of 3)

- The best way of selecting two groups of 1s form our simple Kmap is shown below.
- We see that both groups are powers of two and that the groups overlap.
- The next slide gives
 guidance for selecting Kmap groups.


### 3.4.3 Kmap Simplification for Two Variables (3 of 3)

- The rules of Kmap simplification are:
- Groupings can contain only 1s; no 0s.
- Groups can be formed only at right angles; diagonal groups are not allowed.
- The number of 1 s in a group must be a power of 2 - even if it contains a single 1 .
- The groups must be made as large as possible.
- Groups can overlap and wrap around the sides of the Kmap.


### 3.4.4 Kmap Simplification for Three Variables (1 of 7)

- A Kmap for three variables is constructed as shown in the diagram below.
- We have placed each minterm in the cell that will hold its value.
- Notice that the values for the yz combination at the top of the matrix form a pattern that is not a normal binary sequence.



### 3.4.4 Kmap Simplification for Three Variables (2 of 7)

- Thus, the first row of the Kmap contains all minterms where $x$ has a value of zero.
- The first column contains all minterms where $y$ and $z$ both have a value of zero.

| yz <br> $\mathbf{x}$ <br> $\mathbf{x}$ <br> 0 |  | 00 | 01 | 11 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
| 1 |  |  |  |  |  |

### 3.4.4 Kmap Simplification for Three Variables (3 of 7)

- Consider the function: $\mathbf{F}(X, Y, Z)=X^{\prime} Y^{\prime} Z+X^{\prime} Y Z+X Y^{\prime} Z+X Y Z$
- Its Kmap is given below.
- What is the largest group of 1 s that is a power of 2?

| YZ |  | 00 | 01 | 11 |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 1 | 10 |  |
| 1 | 0 | 1 | 1 | 0 |

### 3.4.4 Kmap Simplification for Three Variables (4 of 7)

- This grouping tells us that changes in the variables $x$ and $y$ have no influence upon the value of the function: They are
 irrelevant.
- This means that the function,

$$
\begin{aligned}
& \mathbf{F}(\mathbf{X}, \mathbf{Y}, \mathbf{Z})=\mathbf{X}^{\prime} \mathbf{Y}^{\prime} \mathbf{Z}+\mathbf{X}^{\prime} \mathbf{Y Z}+\mathbf{X} \mathbf{Y}^{\prime} \mathbf{Z}+\mathbf{X Y Z} \\
& \quad \text { reduces to } F(x)=z .
\end{aligned}
$$

> You could verify this reduction with identities or a truth table.

### 3.4.4 Kmap Simplification for Three Variables (5 of 7)

- Now for a more complicated Kmap. Consider the function:

$$
\begin{aligned}
F(X, Y, Z)= & X^{\prime} Y^{\prime} Z^{\prime}+X^{\prime} Y^{\prime} Z+X X^{\prime} Y Z \\
& +X^{\prime} Y Z^{\prime}+X Y^{\prime} Z^{\prime}+X Y Z
\end{aligned}
$$

- Its Kmap is shown below. There are (only) two groupings of 1s.
- Can you find them?

|  | 00 | 01 | 11 | 10 |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 1 | 1 | 1 |
| 1 | 1 | 0 | 0 | 1 |

### 3.4.4 Kmap Simplification for Three Variables (6 of 7)

- In this Kmap, we see an example of a group that wraps around the sides of a Kmap.
- This group tells us that the values of $x$ and $y$ are not relevant to the term of the function that is encompassed by the group.
- What does this tell us about this term of the function?

> What about the green group in the top row?

### 3.4.4 Kmap Simplification for Three Variables (7 of 7)

- The green group in the top row tells us that only the value of $x$ is significant in that group.
- We see that it is complemented in that row, so the other term of the reduced function is $\mathbf{X}^{\prime}$
- Our reduced function is $\mathbf{F}(\mathbf{X}, \mathbf{Y}, \mathbf{Z})=\mathbf{X}^{\prime}+\mathbf{Z}^{\prime}$

Recall that we had six minterms in our original function!


### 3.4.5 Kmap Simplification for Four Variables (1 of 4)

- Our model can be extended to accommodate the 16 minterms that are produced by a four-input function.
- This is the format for a 16 -minterm Kmap:

| $y z$ | 00 | 01 | 11 | 10 |
| ---: | :---: | :---: | :---: | :---: |
| $w x$ | 00 | $w^{\prime} x^{\prime} y^{\prime} z^{\prime}$ | $w^{\prime} x^{\prime} y^{\prime} z$ | $w^{\prime} x y$ |
| 01 | $w^{\prime} x y^{\prime} z^{\prime}$ | $w^{\prime} x y^{\prime} z$ | $w^{\prime} x^{\prime} y z^{\prime}$ |  |
| 11 | $w x^{\prime} y^{\prime} z^{\prime}$ | $w x^{\prime} y^{\prime} z$ | $w x y z$ | $w^{\prime} x y z^{\prime}$ |
| 10 | $w x y^{\prime} z^{\prime}$ | $w x y^{\prime} z$ | $w x y z$ | $w x z^{\prime}$ |

### 3.4.5 Kmap Simplification for Four Variables (2 of 4)

- We have populated the Kmap shown below with the nonzero minterms from the function:
$\mathbf{F}(\mathbf{W}, \mathbf{X}, \mathbf{Y}, \mathbf{Z})=\mathbf{W}^{\prime} \mathbf{X}^{\prime} \mathbf{Y}^{\prime} \mathbf{Z}^{\prime}+\mathbf{W}^{\prime} \mathbf{X}^{\prime} \mathbf{Y}^{\prime} \mathbf{Z}+\mathbf{W}^{\prime} \mathbf{X}^{\prime} \mathbf{Y} \mathbf{Z}^{\prime}$ $+W^{\prime} X Y Z^{\prime}+W X^{\prime} Y^{\prime} Z^{\prime}+W X^{\prime} Y^{\prime} Z+W X^{\prime} Y Z^{\prime}$
- Can you identify (only) three groups in this Kmap?

Recall that groups can overlap.

| $Y Z$ |  | 00 | 01 | 11 |
| :---: | :---: | :---: | :---: | :---: |
| WX | 00 |  |  |  |
| 00 | 1 | 1 |  | 1 |
| 01 |  |  |  | 1 |
| 11 |  |  |  |  |
| 10 | 1 | 1 |  | 1 |
|  |  |  |  |  |

### 3.4.5 Kmap Simplification for Four Variables (3 of 4)

- Our three groups consist of:
- A purple group entirely within the Kmap at the right.
- A pink group that wraps the top and bottom.
- A green group that spans the corners.
- Thus we have three terms in our final function:

$$
\begin{aligned}
F(W, X, Y, Z)= & X^{\prime} Y^{\prime}
\end{aligned}+X^{\prime} Z^{\prime}, ~+~ W^{\prime} Y Z^{\prime} .
$$



### 3.4.5 Kmap Simplification for Four Variables (4 of 4)

- It is possible to have a choice as to how to pick groups within a Kmap, while keeping the groups as large as possible.
- The (different) functions that result from the groupings below are logically equivalent.



### 3.4.6 Don't Care Conditions (1 of 5)

- Real circuits don't always need to have an output defined for every possible input.
- For example, some calculator displays consist of 7segment LEDs. These LEDs can display $2^{7}-1$ patterns, but only ten of them are useful.
- If a circuit is designed so that a particular set of inputs can never happen, we call this set of inputs a don't care condition.
- They are very helpful to us in Kmap circuit simplification.


### 3.4.6 Don't Care Conditions (2 of 5)

- In a Kmap, a don't care condition is identified by an $X$ in the cell of the minterm(s) for the don't care inputs, as shown here.
- In performing the simplification, we are free to include or ignore the $X^{\prime}$ s when creating our groups.


### 3.4.6 Don't Care Conditions (3 of 5)

- In one grouping in the Kmap below, we have the function:

$$
F(W, X, Y, Z)=W^{\prime} X^{\prime}+Y Z
$$



### 3.4.6 Don't Care Conditions (4 of 5)

- A different grouping gives us the function:
$\mathrm{F}(\mathrm{W}, \mathrm{X}, \mathrm{Y}, \mathrm{Z})=\mathrm{W}^{\prime} \mathrm{Z}+\mathrm{YZ}$



### 3.4.6 Don't Care Conditions (5 of 5)

- The truth table of:
$F(W, X, Y, Z)=W^{\prime} X^{\prime}+Y Z$

| YZ | 00 | 01 | 11 | 10 |
| :---: | :---: | :---: | :---: | :---: |
| $W X$ | $X$ | 1 | 1 | $X$ |
| 00 |  | $X$ | 1 |  |
| 01 |  | 1 |  |  |
| 11 | $X$ |  | 1 |  |
| 10 |  |  |  |  |

differs from the truth table of:
$\mathbf{F}(\mathbf{W}, \mathbf{X}, \mathbf{Y}, \mathbf{Z})=\mathbf{W}^{\prime} \mathbf{Z}+\mathbf{Y Z}$


- However, the values for which they differ, are the inputs for which we have don't care conditions.


### 3.4.7 Summary (1 of 2)

- Kmaps provide an easy graphical method of simplifying Boolean expressions.
- A Kmap is a matrix consisting of the outputs of the minterms of a Boolean function.
- In this section, we have discussed 2-, $3-$, and 4 input Kmaps. This method can be extended to any number of inputs through the use of multiple tables.


### 3.4.7 Summary (2 of 2 )

- Recapping the rules of Kmap simplification:
- Groupings can contain only 1s; no Os.
- Groups can be formed only at right angles; diagonal groups are not allowed.
- The number of 1 s in a group must be a power of 2 - even if it contains a single 1.
- The groups must be made as large as possible.
- Groups can overlap and wrap around the sides of the Kmap.
- Use don't care conditions when you can.


### 3.5 Digital Components (1 of 8)

- The main thing to remember is that combinations of gates implement Boolean functions.

- The circuit above implements the Boolean function $F(x, y, z)=\mathbf{x}+\mathbf{y}^{\prime} \mathbf{z}$ :

We simplify our Boolean expressions so
that we can create simpler circuits.

### 3.5 Digital Components (2 of 8)

- Standard digital components are combined into single integrated circuit packages.
- Boolean logic can be used to implement the desired functions.



### 3.5 Digital Components (3 of 8)

- The Boolean circuit:

- Can be rendered using only NAND gates as:



### 3.5 Digital Components (4 of 8)

- So we can wire the pre-packaged circuit to implement our function:



### 3.5 Digital Components (5 of 8)

- Boolean logic is used to solve practical problems.
- Expressed in terms of Boolean logic practical problems can be expressed by truth tables.
- Truth tables can be readily rendered into Boolean logic circuits.


### 3.5 Digital Components (6 of 8)

- Suppose we are to design a logic circuit to determine the best time to plant a garden.
- We consider three factors (inputs):
- (1) time, where 0 represents day and 1 represents evening;
- (2) moon phase, where 0 represents not full and 1 represents full; and
- (3) temperature, where 0 represents $45^{\circ} \mathrm{F}$ and below, and 1 represents over $45^{\circ} \mathrm{F}$.
- We determine that the best time to plant a garden is during the evening with a full moon.


### 3.5 Digital Components (7 of 8)

- This results in the following truth table:

| Time $(\boldsymbol{x})$ | Moon $(\boldsymbol{y})$ | Temperature (z) | Plant? |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

### 3.5 Digital Components (8 of 8)

- From the truth table, we derive the circuit:

| Time $(\boldsymbol{x})$ | Moon $(\boldsymbol{y})$ | Temperature (z) | Plant? |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 0 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |
| 1 | 1 | 1 | 1 |

$$
F(x, y, z)=x y z^{\prime}+x y z=x y
$$



### 3.6 Combinational Circuits (1 of 12)

- We have designed a circuit that implements the Boolean function:

$$
F(X, Y, Z)=X+Y^{\prime} Z
$$

- This circuit is an example of a combinational logic circuit.
- Combinational logic circuits produce a specified output (almost) at the instant when input values are applied.
- In a later section, we will explore circuits where this is not the case.


### 3.6 Combinational Circuits (2 of 12)

- Combinational logic circuits give us many useful devices.
- One of the simplest is the half adder, which finds the sum of two bits.
- We can gain some insight as to the construction of a half adder by looking at its truth table, shown at the right.


### 3.6 Combinational Circuits (3 of 12)

- As we see, the sum can be found using the XOR operation and the carry using the AND operation.


| Inputs | Outputs |  |  |
| :---: | :---: | :---: | :---: |
| $X$ | $Y$ | Sum | Carry |
| 0 | 0 | 0 | 0 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 1 | 0 |
| 1 | 1 | 0 | 1 |

### 3.6 Combinational Circuits (4 of 12)

- We can change our half adder into to a full adder by including gates for processing the carry bit.
- The truth table for a full adder is shown at the right.

Inputs Outputs

| X | Carry |  | Carry |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Y | In | Sum | Out |
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 1 |
| 1 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 |

### 3.6 Combinational Circuits (5 of 12)

- How can we change the half adder shown below to make it a full adder?


| $c$ | Inputs |  | Outputs |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Y Carry | Carry |  |  |
| X | Y | In | Sum | Out |
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 1 |
| 1 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 |

### 3.6 Combinational Circuits (6 of 12)

- Here's our completed full adder.


| $c$ | Inputs |  | Outputs |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Carry | Carry <br> $X$ |  | Y |
| In | Sum | Out |  |  |
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 0 | 1 | 0 |
| 0 | 1 | 1 | 0 | 1 |
| 1 | 0 | 0 | 1 | 0 |
| 1 | 0 | 1 | 0 | 1 |
| 1 | 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 1 | 1 |

### 3.6 Combinational Circuits (7 of 12)

- Just as we combined half adders to make a full adder, full adders can connected in series.
- The carry bit "ripples" from one adder to the next; hence, this configuration is called a ripple-carry adder.


Today's systems employ more efficient adders.

### 3.6 Combinational Circuits (8 of 12)

- Decoders are another important type of combinational circuit.
- Among other things, they are useful in selecting a memory location according a binary value placed on the address lines of a memory bus.
- Address decoders with $n$ inputs can select any of $2^{n}$ locations.

This is a block diagram for a decoder.


### 3.6 Combinational Circuits (9 of 12)

- This is what a 2-to-4 decoder looks like on the inside.

If $x=0$ and $y=1$, which output line is enabled?


### 3.6 Combinational Circuits (10 of 12)

- A multiplexer does just the opposite of a decoder.
- It selects a single output from several inputs.
- The particular input chosen for output is determined by the value of the multiplexer's control lines.
- To be able to select among $n$


Control lines inputs, $\log _{2} n$ control lines are needed.

- This is a block diagram for a multiplexer.


### 3.6 Combinational Circuits (11 of 12)

- This is what a 4-to-1 multiplexer looks like on the inside.


If $S_{0}=1$ and $S_{1}=0$, which input is
transferred to the output?

### 3.6 Combinational Circuits (12 of 12)

- This shifter moves the bits of a nibble one position to the left or right.

If $S=0$, in which direction do the
 input bits shift?

### 3.7 Sequential Circuits (1 of 30)

- Combinational logic circuits are perfect for situations when we require the immediate application of a Boolean function to a set of inputs.
- There are other times, however, when we need a circuit to change its value with consideration to its current state as well as its inputs.
- These circuits have to "remember" their current state.
- Sequential logic circuits provide this functionality for us.


### 3.7 Sequential Circuits (2 of 30)

- As the name implies, sequential logic circuits require a means by which events can be sequenced.
- State changes are controlled by clocks.
- A "clock" is a special circuit that sends electrical pulses through a circuit.
- Clocks produce electrical waveforms such as the one shown below.



### 3.7 Sequential Circuits (3 of 30)

- State changes occur in sequential circuits only when the clock ticks.
- Circuits can change state on the rising edge, falling edge, or when the clock pulse reaches its highest voltage.



### 3.7 Sequential Circuits (4 of 30)

- Circuits that change state on the rising edge, or falling edge of the clock pulse are called edge-triggered.
- Level-triggered circuits change state when the clock voltage reaches its highest or lowest level.



### 3.7 Sequential Circuits (5 of 30)

- To retain their state values, sequential circuits rely on feedback.
- Feedback in digital circuits occurs when an output is looped back to the input.
- A simple example of this concept is shown below.
- If $Q$ is 0 it will always be 0 , if it is 1 , it will always be 1 . Why?



### 3.7 Sequential Circuits (6 of 30)

- You can see how feedback works by examining the most basic sequential logic components, the SR flip-flop.
- The "SR" stands for set/reset.
- The internals of an SR flip-flop are shown below, along with its block diagram.



### 3.7 Sequential Circuits (7 of 30)

- The behavior of an SR flip-flop is described by a characteristic table.
- $\mathrm{Q}(\mathrm{t})$ means the value of the output at time t . $\mathrm{Q}(\mathrm{t}+1)$ is the value of Q after the next clock pulse.


| $S$ | $R$ | $Q(t+1)$ |
| :--- | :--- | :--- |
| 0 | 0 | $Q(t)$ (no change) |
| 0 | 1 | 0 (reset to 0$)$ |
| 1 | 0 | 1 (set to 1$)$ |
| 1 | 1 | undefined |

### 3.7 Sequential Circuits (8 of 30)

- The SR flip-flop actually has three inputs: $S, R$, and its current output, Q.
- Thus, we can construct a truth table for this circuit, as shown at the right.
- Notice the two undefined values. When both $S$ and $R$

|  | Present <br> State | Next <br> State |  |
| :---: | :---: | :---: | :---: |
| $S$ | $R$ | $Q(t)$ | $Q(t+1)$ |
| 0 | 0 | 0 | 0 |
| 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 |
| 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 |
| 1 | 1 | 0 | undefined |
| 1 | 1 | 1 | undefined |
|  |  |  |  | are 1 , the $\operatorname{SR}$ flip-flop is unstable.

### 3.7 Sequential Circuits (9 of 30)

- If we can be sure that the inputs to an SR flip-flop will never both be 1, we will never have an unstable circuit. This may not always be the case.
- The SR flip-flop can be modified
 to provide a stable state when both inputs are 1.
- This modified flip-flop is called a JK flip-flop, shown at the right.


### 3.7 Sequential Circuits (10 of 30)

- At the right, we see how an SR flip-flop can be modified to create a JK flip-flop.

- The characteristic table indicates that the flip-flop is stable for all inputs.

| $J$ | $K$ | $Q(t+1)$ |
| :--- | :--- | :--- |
| 0 | 0 | $Q(t)$ (no change) |
| 0 | 1 | 0 (reset to 0$)$ |
| 1 | 0 | 1 (set to 1$)$ |
| 1 | 1 | $Q(t)$ |

### 3.7 Sequential Circuits (11 of 30)

- Another modification of the SR flip-flop is the D flipflop, shown below with its characteristic table.

- You will notice that the output of the flip-flop remains the same during subsequent clock pulses. The output changes only when the value of $D$
 changes.


### 3.7 Sequential Circuits (12 of 30)

- The $D$ flip-flop is the fundamental circuit of computer memory.
- D flip-flops are usually illustrated using the block diagram shown below.
- The characteristic table for the D flip-flop is shown at the right.



### 3.7 Sequential Circuits (13 of 30)

- The behavior of sequential circuits can be expressed using characteristic tables or finite state machines (FSMs).
- FSMs consist of a set of nodes that hold the states of the machine and a set of arcs that connect the states.
- Moore and Mealy machines are two types of FSMs that are equivalent.
- They differ only in how they express the outputs of the machine.
- Moore machines place outputs on each node, while Mealy machines present their outputs on the transitions.


### 3.7 Sequential Circuits (14 of 30)

- The behavior of a JK flop-flop is depicted below by a Moore machine (left) and a Mealy machine (right).



### 3.7 Sequential Circuits (15 of 30)

- Although the behavior of Moore and Mealy machines is identical, their implementations differ.
- This is our Moore machine.



### 3.7 Sequential Circuits (16 of 30)

- Although the behavior of Moore and Mealy machines is identical, their implementations differ.
- This is our Mealy machine



### 3.7 Sequential Circuits (17 of 30 )

- It is difficult to express the complexities of actual implementations using only Moore and Mealy machines.
- For one thing, they do not address the intricacies of timing very well.
- Secondly, it is often the case that an interaction of numerous signals is required to advance a machine from one state to the next.
- For these reasons, Christopher Clare invented the algorithmic state machine (ASM).
- The next slide illustrates the components of an ASM.


### 3.7 Sequential Circuits (18 of 30)

State Block


### 3.7 Sequential Circuits (19 of 30)

- This is an ASM for a microwave oven.



### 3.7 Sequential Circuits (20 of 30)

- Sequential circuits are used anytime that we have a "stateful" application.
- A stateful application is one where the next state of the machine depends on the current state of the machine and the input.
- A stateful application requires both combinational and sequential logic.
- The following slides provide several examples of circuits that fall into this category.
- Can you think of others?


### 3.7 Sequential Circuits (21 of 30)

- This illustration shows a 4-bit register consisting of D flip-flops. You will usually see its block diagram (below) instead.


A larger memory configuration is shown on the next slide.

### 3.7 Sequential Circuits (22 of 30)



### 3.7 Sequential Circuits (23 of 30 )

- A binary counter is another example of a sequential circuit.
- The low-order bit is complemented at each clock pulse.
- Whenever it changes from 0 to 1 , the next bit is complemented, and so on through the other flip-
 flops.


### 3.7 Sequential Circuits (24 of 30 )

- Convolutional coding and decoding requires sequential circuits.
- One important convolutional code is the $(2,1)$ convolutional code that underlies the PRML code that is briefly described at the end of Chapter 2.
- A $(2,1)$ convolutional code is so named because two symbols are output for every one symbol input.
- A convolutional encoder for PRML with its characteristic table is shown on the next slide.


### 3.7 Sequential Circuits (25 of 30)

| Input <br> A | Current <br> State <br> B C | Next state <br> B C | output | Input <br> A | Current <br> State <br> B C | Next state <br> B C | Output |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 00 | 00 | 00 | 0 | 10 | 01 | 10 |
| 1 | 00 | 10 | 11 | 1 | 10 | 11 | 01 |
| 0 | 01 | 00 | 11 | 0 | 11 | 01 | 01 |
| 1 | 01 | 10 | 00 | 1 | 11 | 11 | 10 |



### 3.7 Sequential Circuits (26 of 30)

- This is the Mealy machine for our encoder.


| Input <br> A | Current <br> state <br> B C | Next State <br> B C | Output |
| :---: | :---: | :---: | :---: |
| 0 | 00 | 00 | 00 |
| 1 | 00 | 10 | 11 |
| 0 | 01 | 00 | 11 |
| 1 | 01 | 10 | 00 |
| 0 | 10 | 01 | 10 |
| 1 | 10 | 11 | 01 |
| 0 | 11 | 01 | 01 |
| 1 | 11 | 11 | 10 |

### 3.7 Sequential Circuits (27 of 30)

- The fact that there is a limited set of possible state transitions in the encoding process is crucial to the error correcting capabilities of PRML.
- You can see by our Mealy machine for encoding that:


$$
F(11010010)=1101010010111110 .
$$

### 3.7 Sequential Circuits (28 of 30)

- The decoding of our code is provided by inverting the inputs and outputs of the Mealy machine for the encoding process.
- You can see by our Mealy machine for decoding that:

$$
F\left(\begin{array}{llllllll}
11 & 01 & 01 & 00 & 10 & 11 & 11 & 10
\end{array}\right)=11010010
$$

### 3.7 Sequential Circuits (29 of 30)

- Yet another way of looking at the decoding process is through a lattice diagram.
- Here we have plotted the state transitions based on the input (top) and showing the output at the bottom for the
 string 00101111.

$$
F\left(\begin{array}{llll}
00 & 10 & 11 & 11
\end{array}\right)=1001
$$

### 3.7 Sequential Circuits (30 of 30)

- Suppose we receive the erroneous string: 10101111.
- Here we have plotted the accumulated errors based on the allowable transitions.
- The path of least error outputs 1001, thus
 1001 is the string of maximum likelihood.

$$
F\left(\begin{array}{llll}
00 & 10 & 11 & 11
\end{array}\right)=1001
$$

### 3.8 Designing Circuits (1 of 3)

- We have seen digital circuits from two points of view: digital analysis and digital synthesis.
- Digital analysis explores the relationship between a circuits inputs and its outputs.
- Digital synthesis creates logic diagrams using the values specified in a truth table.
- Digital systems designers must also be mindful of the physical behaviors of circuits to include minute propagation delays that occur between the time when a circuit's inputs are energized and when the output is accurate and stable.


### 3.8 Designing Circuits (2 of 3)

- Digital designers rely on specialized software, such as VHDL and Verilog, to create efficient circuits.
- Thus, software is an enabler for the construction of better hardware.
- Of course, software is in reality a collection of algorithms that could just as well be implemented in hardware.
- Recall the Principle of Equivalence of Hardware and Software.


### 3.8 Designing Circuits (3 of 3)

- When we need to implement a simple, specialized algorithm and its execution speed must be as fast as possible, a hardware solution is often preferred.
- This is the idea behind embedded systems, which are small special-purpose computers that we find in many everyday things.
- Embedded systems require special programming that demands an understanding of the operation of digital circuits, the basics of which you have learned in this chapter.


## Conclusion (1 of 3)

- Computers are implementations of Boolean logic.
- Boolean functions are completely described by truth tables.
- Logic gates are small circuits that implement Boolean operators.
- The basic gates are AND, OR, and NOT.
- The XOR gate is very useful in parity checkers and adders.
- The "universal gates" are NOR, and NAND.


## Conclusion (2 of 3)

- Computer circuits consist of combinational logic circuits and sequential logic circuits.
- Combinational circuits produce outputs (almost) immediately when their inputs change.
- Sequential circuits require clocks to control their changes of state.
- The basic sequential circuit unit is the flip-flop: The behaviors of the SR, JK, and D flip-flops are the most important to know.


## Conclusion (3 of 3)

- The behavior of sequential circuits can be expressed using characteristic tables or through various finite state machines.
- Moore and Mealy machines are two finite state machines that model high-level circuit behavior.
- Algorithmic state machines are better than Moore and Mealy machines at expressing timing and complex signal interactions.
- Examples of sequential circuits include memory, counters, and Viterbi encoders and decoders.

