Logic

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Proof methods

- Proof methods divide into (roughly) two kinds:
 - Application of inference rules
 - Legitimate (sound) generation of new sentences from old
 - Proof = a sequence of inference rule applications Can use inference rules as operators in a standard search
 - algorithm
 - Typically require transformation of sentences into a normal form

- Model checking

- truth table enumeration (always exponential in n)
- improved backtracking, e.g., Davis--Putnam-Logemann-Loveland (DPLL)
- heuristic search in model space (sound but incomplete)
 - e.g., min-conflicts-like hill-climbing algorithms

Resolution

Conjunctive Normal Form (CNF) conjunction of disjunctions of literals clauses E.g., (A v ¬B) ∧ (B v ¬C v ¬D)

 $\begin{array}{c|c} \textbf{Resolution inference rule (for CNF):} \\ \hline & \begin{matrix} l_{i} \lor \ldots \lor l_{k}, \end{matrix} & \begin{matrix} m_{1} \lor \ldots \lor m_{n} \end{matrix} \\ \hline & \begin{matrix} l_{i} \lor \ldots \lor l_{i-1} \lor l_{i+1} \lor \ldots \lor l_{k} \lor m_{1} \lor \ldots \lor m_{i-1} \lor m_{i+1} \lor \ldots \lor m_{n} \end{array}$

where l_i and m_j are complementary literals. E.g., $P_{1,3} \vee P_{2,2}$, $\neg P_{2,2}$ $P_{1,3}$

 Resolution is sound and complete for propositional logic



Resolution

Soundness of resolution inference rule:

$$\neg (l_{i} \vee \ldots \vee l_{i-1} \vee l_{i+1} \vee \ldots \vee l_{k}) \Rightarrow l_{i}$$

$$\neg m_{j} \Rightarrow (m_{1} \vee \ldots \vee m_{j-1} \vee m_{j+1} \vee \ldots \vee m_{j})$$

$$\neg (l_{i} \vee \ldots \vee l_{i-1} \vee l_{i+1} \vee \ldots \vee l_{k}) \Rightarrow (m_{1} \vee \ldots \vee m_{j-1} \vee m_{j+1} \vee \ldots \vee m_{m_{1}})$$

Conversion to CNF

 $\mathsf{B}_{1,1} \Leftrightarrow (\mathsf{P}_{1,2} \lor \mathsf{P}_{2,1})$

- 1. Eliminate \Leftrightarrow , replacing $\alpha \Leftrightarrow \beta$ with $(\alpha \Rightarrow \beta) \land (\beta \Rightarrow \alpha)$. $(B_{1,1} \Rightarrow (P_{1,2} \lor P_{2,1})) \land ((P_{1,2} \lor P_{2,1}) \Rightarrow B_{1,1})$
- 2. Eliminate \Rightarrow , replacing $a \Rightarrow \beta$ with $\neg a \lor \beta$. ($\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}$) $\land (\neg (P_{1,2} \lor P_{2,1}) \lor B_{1,1})$
- 3. Move \neg inwards using de Morgan's rules and double-negation: ($\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}$) \land (($\neg P_{1,2} \lor \neg P_{2,1}$) $\lor B_{1,1}$)

4. Apply distributivity law (\land over \lor) and flatten: ($\neg B_{1,1} \lor P_{1,2} \lor P_{2,1}$) \land ($\neg P_{1,2} \lor B_{1,1}$) \land ($\neg P_{2,1} \lor B_{1,1}$)

Resolution algorithm

 Proof by contradiction, i.e., show KB^Λ¬α unsatisfiable

function PL-RESOLUTION(*KB*, α) returns *true* or *false*

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clauses \leftarrow the set of clauses in the CNF representation of KB \land \neg \alpha

new \leftarrow \{ \}

loop do

for each C_i, C_j in clauses do

resolvents \leftarrow PL-RESOLVE(C_i, C_j)

if resolvents contains the empty clause then return true

new \leftarrow new \cup resolvents

if new \subseteq clauses then return false

clauses \leftarrow clauses \cup new
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Resolution example

• $KB = (B_{1,1} \Leftrightarrow (P_{1,2} \lor P_{2,1})) \land \neg B_{1,1} \alpha = \neg P_{1,2}$



Forward and backward chaining

- Horn Form (restricted)
 - KB = conjunction of Horn clauses
 - Horn clause =
 - proposition symbol; or
 - (conjunction of symbols) \Rightarrow symbol
 - E.g., $C \land (B \Rightarrow A) \land (C \land D \Rightarrow B)$
- Modus Ponens (for Horn Form): complete for Horn KBs

$$\begin{array}{ccc} \alpha_1, \dots, \alpha_n, & \alpha_1 \wedge \dots \wedge \alpha_n \Longrightarrow \beta \\ \end{array}$$

- Can be used with forward chaining or backward chaining.
- These algorithms are very natural and run in linear time

Forward chaining

 Idea: fire any rule whose premises are satisfied in the KB,

- add its conclusion to the KB, until query is found

 $P \Rightarrow Q$ $L \land M \Rightarrow P$ $B \land L \Rightarrow M$ $A \land P \Rightarrow L$ $A \land B \Rightarrow L$ AB



Forward chaining algorithm

function PL-FC-ENTAILS?(KB, q) returns true or false local variables: count, a table, indexed by clause, initially the number of premises inferred, a table, indexed by symbol, each entry initially false agenda, a list of symbols, initially the symbols known to be true

while agenda is not empty do

 $p \leftarrow \text{POP}(agenda)$ unless inferred[p] do $inferred[p] \leftarrow true$ for each Horn clause c in whose premise p appears do decrement count[c]if count[c] = 0 then do if HEAD[c] = q then return truePUSH(HEAD[c], agenda)

return false

Forward chaining is sound and complete for Horn KB

















Proof of completeness

- FC derives every atomic sentence that is entailed by *KB*
- 1. FC reaches a fixed point where no new atomic sentences are derived
- 2. Consider the final state as a model *m*, assigning true/false to symbols
- 3. Every clause in the original *KB* is true in *m* $a_1 \land \dots \land a_{k \Rightarrow} b$
- 4. Hence *m* is a model of *KB*
- 5. If $KB \models q$, q is true in every model of KB, including m

Backward chaining

Idea: work backwards from the query q:

to prove *q* by BC, check if *q* is known already, or prove by BC all premises of some rule concluding *q*

Avoid loops: check if new subgoal is already on the goal stack

Avoid repeated work: check if new subgoal

- 1. has already been proved true, or
- 2. has already failed





















Forward vs. backward chaining

- FC is data-driven, automatic, unconscious processing,
 - e.g., object recognition, routine decisions
- May do lots of work that is irrelevant to the goal
- BC is goal-driven, appropriate for problem-solving,
 e.g., Where are my keys? How do I get into a PhD program?
- Complexity of BC can be much less than linear in size of KB

Efficient propositional inference

Two families of efficient algorithms for propositional inference:

Complete backtracking search algorithms

- DPLL algorithm (Davis, Putnam, Logemann, Loveland)
- Incomplete local search algorithms
 - WalkSAT algorithm

The DPLL algorithm

Determine if an input propositional logic sentence (in CNF) is satisfiable.

Improvements over truth table enumeration:

1. Early termination

A clause is true if any literal is true.

A sentence is false if any clause is false.

2. Pure symbol heuristic

Pure symbol: always appears with the same "sign" in all clauses.

e.g., In the three clauses (A v \neg B), (\neg B v \neg C), (C v A), A and B are pure, C is impure.

Make a pure symbol literal true.

3. Unit clause heuristic

Unit clause: only one literal in the clause The only literal in a unit clause must be true.

The DPLL algorithm

function DPLL-SATISFIABLE?(s) returns true or false
inputs: s, a sentence in propositional logic

 $clauses \leftarrow$ the set of clauses in the CNF representation of s $symbols \leftarrow$ a list of the proposition symbols in sreturn DPLL(clauses, symbols, [])

function DPLL(clauses, symbols, model) returns true or false

if every clause in *clauses* is true in *model* then return *true* if some clause in *clauses* is false in *model* then return *false* $P, value \leftarrow \text{FIND-PURE-SYMBOL}(symbols, clauses, model)$ if P is non-null then return DPLL(clauses, symbols-P, [P = value|model]) $P, value \leftarrow \text{FIND-UNIT-CLAUSE}(clauses, model)$ if P is non-null then return DPLL(clauses, symbols-P, [P = value|model]) $P \leftarrow \text{FIRST}(symbols); rest \leftarrow \text{REST}(symbols)$ return DPLL(clauses, rest, [P = true|model]) or DPLL(clauses, rest, [P = false|model])

The WalkSAT algorithm

- Incomplete, local search algorithm
- Evaluation function: The min-conflict heuristic of minimizing the number of unsatisfied clauses
- Balance between greediness and randomness

The WalkSAT algorithm

function WALKSAT(clauses, p, max-flips) returns a satisfying model or failure
inputs: clauses, a set of clauses in propositional logic

p, the probability of choosing to do a "random walk" move max-flips, number of flips allowed before giving up

 $model \leftarrow a random assignment of true/false to the symbols in clauses$

for i = 1 to max-flips do

if model satisfies clauses then return model

 $clause \leftarrow a randomly selected clause from clauses that is false in model$

with probability p flip the value in model of a randomly selected symbol
from clause

else flip whichever symbol in *clause* maximizes the number of satisfied clauses return *failure*

Hard satisfiability problems

Consider random 3-CNF sentences. e.g.,
 (¬D v ¬B v C) ∧ (B v ¬A v ¬C) ∧ (¬C v ¬B v E) ∧ (E v ¬D v B) ∧ (B v E v ¬C)

m = number of clauses n = number of symbols

- Hard problems seem to cluster near m/n = 4.3 (critical point)

Hard satisfiability problems



Hard satisfiability problems



 Median runtime for 100 satisfiable random 3-CNF sentences, n = 50

Inference-based agents in the wumpus world

A wumpus-world agent using propositional logic:

$$\begin{array}{l} \neg P_{1,1} \\ \neg W_{1,1} \\ B_{x,y} \Leftrightarrow (P_{x,y+1} \lor P_{x,y-1} \lor P_{x+1,y} \lor P_{x-1,y}) \\ S_{x,y} \Leftrightarrow (W_{x,y+1} \lor W_{x,y-1} \lor W_{x+1,y} \lor W_{x-1,y}) \\ W_{1,1} \lor W_{1,2} \lor \ldots \lor W_{4,4} \\ \neg W_{1,1} \lor \neg W_{1,2} \\ \neg W_{1,1} \lor \neg W_{1,3} \end{array}$$

. . .

 \Rightarrow 64 distinct proposition symbols, 155 sentences

function PL-WUMPUS-AGENT(percept) returns an action inputs: percept, a list, [stench, breeze, glitter] static: KB, initially containing the "physics" of the wumpus world x, y, orientation, the agent's position (init. [1,1]) and orient. (init. right) visited, an array indicating which squares have been visited, initially false action, the agent's most recent action, initially null *plan*, an action sequence, initially empty update x, y, orientation, visited based on action if stench then TELL(KB, $S_{x,y}$) else TELL(KB, $\neg S_{x,y}$) if breeze then TELL(KB, $B_{x,y}$) else TELL(KB, $\neg B_{x,y}$) **if** glitter **then** $action \leftarrow grab$ else if *plan* is nonempty then $action \leftarrow POP(plan)$ else if for some fringe square [i,j], ASK $(KB, (\neg P_{i,j} \land \neg W_{i,j}))$ is true or for some fringe square [i,j], ASK $(KB, (P_{i,j} \vee W_{i,j}))$ is false then do $plan \leftarrow A^*-GRAPH-SEARCH(ROUTE-PB([x, y], orientation, [i, j], visited))$ $action \leftarrow POP(plan)$ else $action \leftarrow a$ randomly chosen move return action

Expressiveness limitation of propositional logic

- KB contains "physics" sentences for every single square
- *• For every time *t* and every location [x, y], $L_{x,y} \wedge FacingRight^{t} \wedge Forward^{t} \Rightarrow L_{x+1,y}$
 - Rapid proliferation of clauses

Summary

- Logical agents apply inference to a knowledge base to derive new information and make decisions
- Basic concepts of logic:
 - syntax: formal structure of sentences
 - semantics: truth of sentences wrt models
 - entailment: necessary truth of one sentence given another
 - inference: deriving sentences from other sentences
 - soundness: derivations produce only entailed sentences
 - completeness: derivations can produce all entailed sentences
- Wumpus world requires the ability to represent partial and negated information, reason by cases, etc.
- Resolution is complete for propositional logic Forward, backward chaining are linear-time, complete for Horn clauses
- Propositional logic lacks expressive power