

Chapter 10: Trees

**Data Abstraction & Problem Solving with
C++
Fifth Edition**
by Frank M. Carrano



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Categories of Data-Management Operations

- General: Operations that
 - Insert data into a data collection
 - Delete data from a data collection
 - Ask questions about the data in a data collection
- Position-oriented ADTs: Operations that
 - Insert data into the i^{th} position
 - Delete data from the i^{th} position
 - Ask a question about the data in the i^{th} position
 - Examples: list, stack, queue, binary tree

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Categories of Data-Management Operations

- Value-oriented ADTs: Operations that
 - Insert data according to its value
 - Delete data knowing only its value
 - Ask a question about data knowing only its value
 - Examples: sorted list, binary search tree

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Terminology

- Trees are composed of nodes and edges
- Trees are hierarchical
 - Parent-child relationship between two nodes
 - Ancestor-descendant relationships among nodes
- Subtree of a tree: Any node and its descendants

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Terminology

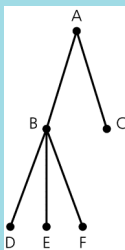


Figure 10-1 A general tree

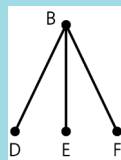


Figure 10-2
A subtree of the tree in Figure 10-1

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Terminology

- General tree
 - A general tree T is a set of one or more nodes such that T is partitioned into disjoint subsets:
 - A single node r , the root
 - Sets that are general trees, called subtrees of r

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Terminology

- Parent of node n
 - The node directly above node n in the tree
- Child of node n
 - A node directly below node n in the tree
- Root
 - The only node in the tree with no parent
- Subtree of node n
 - A tree that consists of a child (if any) of node n and the child's descendants

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Terminology

- Leaf
 - A node with no children
- Siblings
 - Nodes with a common parent
- Ancestor of node n
 - A node on the path from the root to n
- Descendant of node n
 - A node on a path from n to a leaf

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A Binary Tree

- A binary tree is a set T of nodes such that either
 - T is empty, or
 - T is partitioned into three disjoint subsets:
 - A single node r , the root
 - Two possibly empty sets that are binary trees, called the left subtree of r and the right subtree of r

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A General Tree & A Binary Tree

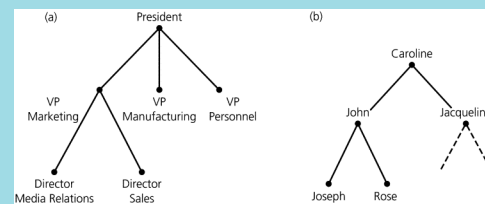


Figure 10-3 (a) An organization chart; (b) a family tree

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More Binary Trees

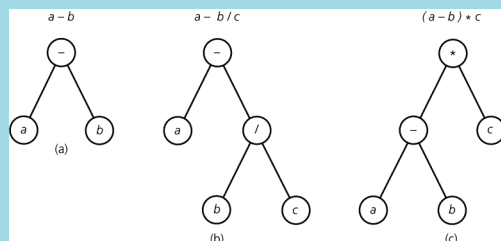


Figure 10-4 Binary trees that represent algebraic expressions

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A Binary Search Tree

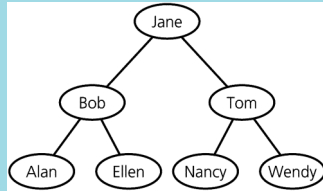
- A binary search tree
 - A binary tree that has the following properties for each node n
 - n 's value is $>$ all values in n 's left subtree T_L
 - n 's value is $<$ all values in n 's right subtree T_R
 - Both T_L and T_R are binary search trees

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A Binary Search Tree

Figure 10-5
A binary search tree of names



The Height of Trees

- Height of a tree
 - Number of nodes along the longest path from the root to a leaf

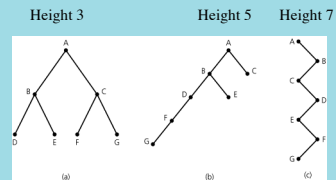


Figure 10-6
Binary trees with the same nodes but different heights

The Height of Trees

- Level of a node n in a tree T
 - If n is the root of T , it is at level 1
 - If n is not the root of T , its level is 1 greater than the level of its parent
- Height of a tree T defined in terms of the levels of its nodes
 - If T is empty, its height is 0
 - If T is not empty, its height is equal to the maximum level of its nodes

The Height of Trees

- A recursive definition of height
 - If T is empty, its height is 0
 - If T is not empty,
$$height(T) = 1 + \max\{height(T_L), height(T_R)\}$$



Full Binary Trees

- A binary tree of height h is *full* if
 - Nodes at levels $< h$ have two children each
- Recursive definition
 - If T is empty, T is a full binary tree of height 0
 - If T is not empty and has height $h > 0$, T is a full binary tree if its root's subtrees are both full binary trees of height $h - 1$

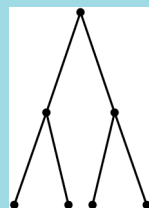


Figure 10-7
A full binary tree of height 3

Complete Binary Trees

- A binary tree of height h is *complete* if
 - It is full to level $h - 1$, and
 - Level h is filled from left to right

Complete Binary Trees

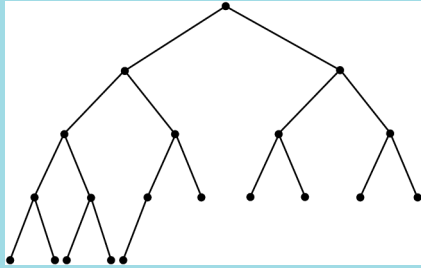


Figure 10-8 A complete binary tree

Complete Binary Trees

Another definition:

- A binary tree of height h is *complete* if
 - All nodes at levels $\leq h - 2$ have two children each, and
 - When a node at level $h - 1$ has children, all nodes to its left at the same level have two children each, and
 - When a node at level $h - 1$ has one child, it is a left child

Balanced Binary Trees

- A binary tree is *balanced* if the heights of any node's two subtrees differ by no more than 1
- Complete binary trees are balanced
- Full binary trees are complete and balanced

The ADT Binary Tree

Binary tree
root
left subtree
right subtree
createBinaryTree()
destroyBinaryTree()
isEmpty()
getRootData()
setRootData()
attachLeft()
attachRight()
attachLeftSubtree()
attachRightSubtree()
detachLeftSubtree()
detachRightSubtree()
getLeftSubtree()
getRightSubtree()
preorderTraverse()
inorderTraverse()
postorderTraverse()

Figure 10-9

UML diagram for the class *BinaryTree*

The ADT Binary Tree

- Building the ADT binary tree in Fig. 10-6b

```
tree1.setRootData('F')
tree1.attachLeft('G')
tree2.setRootData('D')
tree2.attachLeftSubtree(tree1)
tree3.setRootData('B')
tree3.attachLeftSubtree(tree2)
tree3.attachRight('E')
tree4.setRootData('C')
tree10_6.createBinaryTree('A', tree3, tree4)
```

Traversals of a Binary Tree

- A traversal visits each node in a tree
- You do something with or to the node during a visit
 - For example, display the data in the node
- General form of a recursive traversal algorithm


```
traverse (in binTree:BinaryTree)
    if (binTree is not empty)
    { traverse(Left subtree of binTree's root)
      traverse(Right subtree of binTree's root)
    }
```

Traversals of a Binary Tree

- Preorder traversal
 - Visit root before visiting its subtrees
 - i. e. Before the recursive calls
- Inorder traversal
 - Visit root between visiting its subtrees
 - i. e. Between the recursive calls
- Postorder traversal
 - Visit root after visiting its subtrees
 - i. e. After the recursive calls

Traversals of a Binary Tree

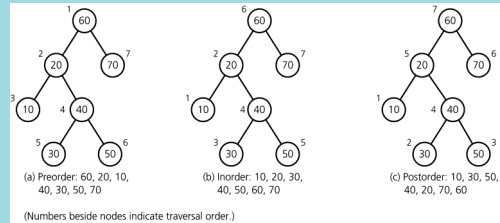


Figure 10-10

Traversals of a binary tree: (a) preorder; (b) inorder; (c) postorder

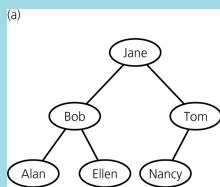
Traversals of a Binary Tree

- A traversal operation can call a function to perform a task on each item in the tree
 - This function defines the meaning of “visit”
 - The client defines and passes this function as an argument to the traversal operation

Possible Representations of a Binary Tree

- An array-based representation
 - Uses an array of tree nodes
 - Requires the creation of a free list that keeps track of available nodes
- A pointer-based representation
 - Nodes have two pointers that link the nodes in the tree

Array-based ADT Binary Tree



tree				
item	leftChild	rightChild	root	
0	Jane	1	2	0
1	Bob	3	4	
2	Tom	5	-1	6
3	Alan	-1	-1	
4	Ellen	-1	-1	
5	Nancy	-1	-1	
6	?	-1	7	Free list
7	?	-1	8	
8	?	-1	9	
*	*	*	*	

Figure 10-11 (a) A binary tree of names; (b) its array-based implementation

Array-based Representation of a Complete Binary Tree

- If a binary tree is complete and remains complete
 - A memory-efficient array-based implementation is possible AND attractive

Array-based Representation of a Complete Binary Tree

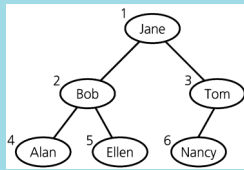


Figure 10-12 Level-by-level numbering of a complete binary tree

0	Jane
1	Bob
2	Tom
3	Alan
4	Ellen
5	Nancy
6	
7	

Figure 10-13 An array-based implementation of the complete tree in Figure 10-12

Pointer-based ADT Binary Tree

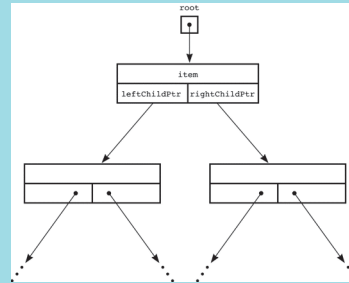


Figure 10-14 A pointer-based implementation of a binary tree

Pointer-based ADT Binary Tree

- `TreeException` and `TreeNode` classes
- `BinaryTree` class
 - Several constructors, including a
 - Protected constructor whose argument is a pointer to a root node; prohibits client access
 - Copy constructor that calls a private function to copy each node during a traversal of the tree
 - Destructor

Pointer-based ADT Binary Tree

- `BinaryTree` class (continued)
 - `isEmpty`, `getRootData`, `setRootData`
 - `attachLeft`, `attachRight`
 - `attachLeftSubtree`, `attachRightSubtree`
 - `detachLeftSubtree`, `detachRightSubtree`
 - `getLeftSubtree`, `getRightSubtree`
 - Overloaded assignment operator

Pointer-based ADT Binary Tree: Tree Traversals

- `BinaryTree` class (continued)
 - Public methods for traversals so that visiting a node remains on the client's side of the wall
- ```
void inorderTraverse(FunctionType visit);
typedef void (*FunctionType) (TreeItemType& item);
```
- Protected methods, such as `inorder`, that enable the recursion
- ```
void inorder(TreeNode *treePtr,
               FunctionType visit);
```
- `inorderTraverse` calls `inorder`, passing it a node pointer and the client-defined function `visit`

Pointer-based ADT Binary Tree: Recursive Inorder Traversal

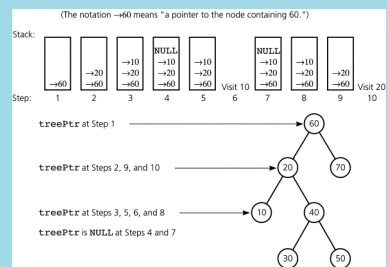


Figure 10-15 Contents of the implicit stack as `treePtr` progresses through a given tree during a recursive inorder traversal

Pointer-based ADT Binary Tree: Nonrecursive Inorder Traversal

- An iterative method and an explicit stack can mimic the actions of a return from a recursive call to inorder

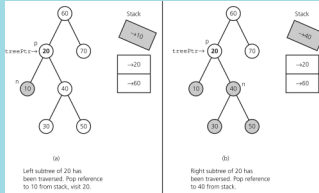


Figure 10-16
Traversing (a) the left and (b) the right subtrees of 20

Copying a Binary Tree

- To copy a tree
 - Traverse it in preorder
 - Insert each item visited into a new tree
 - Use in copy constructor
- To deallocate a tree
 - Traverse in postorder
 - Delete each node visited
 - “Visit” follows deallocation of a node’s subtrees
 - Use in destructor

The ADT Binary Search Tree

- The ADT binary tree is not suitable when you need to search for a particular item
- The ADT binary search tree is suitable for this task
- Record
 - A group of related items, called fields, that are not necessarily of the same data type
- Field
 - A data element within a record

The ADT Binary Search Tree

- A data item in a binary search tree has a specially designated search key
 - A search key is the part of a record that identifies it within a collection of records
- KeyedItem class
 - Contains the search key as a data field and a method for accessing the search key
 - Prevents modification of the search-key value once an item is created
 - Has only a constructor for initializing the search key

The ADT Binary Search Tree

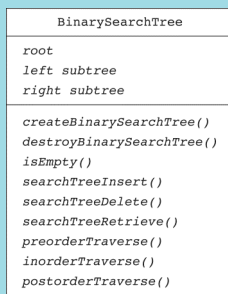


Figure 10-18 UML diagram for the class BinarySearchTree

ADT Binary Search Tree: Search Algorithm

- Search the binary search tree `bst` for the item whose search key is `searchKey`

```

search(in bst:BinarySearchTree,
      in searchKey:KeyType)
    if (bst is empty)
        Item not found
    else if (searchKey equals root item)
        Item is found
    else if (searchKey < root item)
        search(bst's left subtree, searchKey)
    else // searchKey > root item
        search(bst's right subtree, searchKey)
        
```

ADT Binary Search Tree: Insertion

- Insert newItem into the binary search tree to which treePtr points

```
insertItem(in treePtr:TreeNodePtr,
          in newItem:TreeItemType)
    if (Search stops at n's left subtree)
        Make n's leftChildPtr point to newItem
    else
        Make n's rightChildPtr point to newItem
```

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ADT Binary Search Tree: Insertion

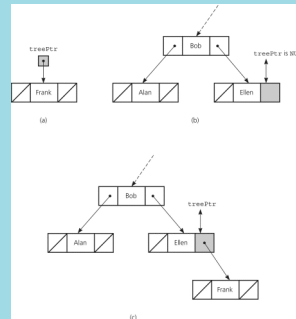


Figure 10-23

- (a) Insertion into an empty tree;
- (b) search terminates at a leaf;
- (c) insertion at a leaf

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ADT Binary Search Tree: Deletion

- Three possible cases for deleting the item in node N
 - N is a leaf
 - Set the pointer in N 's parent to NULL
 - N has only one child
 - Let N 's parent adopt N 's child
 - N has two children

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ADT Binary Search Tree: Deletion

- Deleting the item in node N when N has two children (continued)
 - Locate another node M that is easier to delete
 - M is the leftmost node in N 's right subtree
 - M will have no more than one child
 - M 's search key is called the inorder successor of N 's search key
 - Copy the item that is in M to N
 - Remove the node M from the tree

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ADT Binary Search Tree: Retrieval and Traversal

- The retrieval operation can be implemented by refining the search algorithm
 - Return the item with the desired search key if it exists
 - Otherwise, throw `TreeException`
- Traversals for a binary search tree are the same as the traversals for a binary tree
- Theorem 10-1
 - The inorder traversal of a binary search tree T will visit its nodes in sorted search-key order

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Height of a Binary Tree

- Theorem 10-2
 - A full binary tree of height $h \geq 0$ has $2^h - 1$ nodes
- Theorem 10-3
 - The maximum number of nodes that a binary tree of height h can have is $2^h - 1$
- Theorem 10-4
 - The minimum height of a binary tree with n nodes is $\lceil \log_2(n+1) \rceil$
 - Complete trees and full trees have minimum height
- The maximum height of a binary tree with n nodes is n

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Height of a Binary Tree

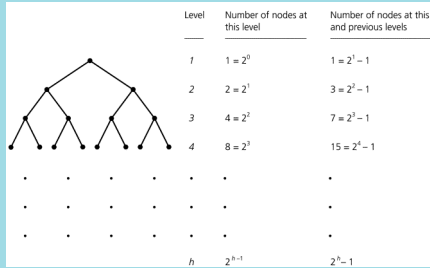


Figure 10-32 Counting the nodes in a full binary tree of height h

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The Efficiency of Binary Search Tree Operations

- The maximum number of comparisons required by any b. s. t. operation is the number of nodes along the longest path from root to a leaf—that is, the tree's height
- The order in which insertion and deletion operations are performed on a binary search tree affects its height
- Insertion in random order produces a binary search tree that has near-minimum height

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The Efficiency of Binary Search Tree Operations

Operation	Average case	Worst case
Retrieval	$O(\log n)$	$O(n)$
Insertion	$O(\log n)$	$O(n)$
Deletion	$O(\log n)$	$O(n)$
Traversal	$O(n)$	$O(n)$

Figure 10-34 The order of the retrieval, insertion, deletion, and traversal operations for the pointer-based implementation of the ADT binary search tree

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Applications

- Treesort
 - Uses the ADT binary search tree to sort an array of records into search-key order
 - Average case: $O(n * \log n)$
 - Worst case: $O(n^2)$

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Applications

- Algorithms for saving a binary search tree
 - Saving a binary search tree and then restoring it to its original shape
 - Uses preorder traversal to save the tree to a file
 - Saving a binary search tree and then restoring it to a balanced shape
 - Uses inorder traversal to save the tree to a file
 - To restore, need the number of nodes in the tree

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The STL Search Algorithms

- *binary_search*
 - Returns true if a specified value appears in the given sorted range
- *lower_bound; upper_bound*
 - Returns an iterator to the first (one past the last) occurrence of a value
- *equal_range*
 - Returns a pair of iterators: One is to the first occurrence of a value in the given sorted range, the other is to one past the last occurrence

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n-ary Trees

- An *n*-ary tree is a general tree whose nodes can have no more than *n* children each
 - A generalization of a binary tree

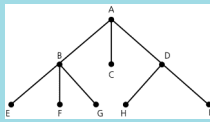


Figure 10-38 A general tree

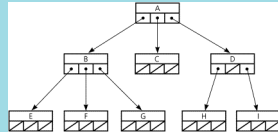


Figure 10-41
An implementation of the *n*-ary tree in Figure 10-38

n-ary Trees

- A binary tree can represent an *n*-ary tree

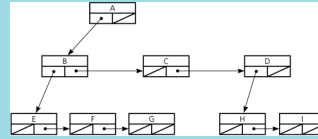


Figure 10-39 Another implementation of the tree in Figure 10-38

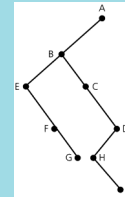


Figure 10-40 The binary tree that Figure 10-39 represents

Summary

- Binary trees provide a hierarchical organization of data
- The implementation of a binary tree is usually pointer-based
- If the binary tree is complete, an efficient array-based implementation is possible
- Traversing a tree to “visit”—that is, do something to or with—each node is useful
- You pass a client-defined “visit” function to the traversal operation to customize its effect on the items in the tree

Summary

- The binary search tree allows you to use a binary search-like algorithm to search for an item having a specified value
- Binary search trees come in many shapes
 - The height of a binary search tree with *n* nodes can range from a minimum of $\lceil \log_2(n + 1) \rceil$ to a maximum of *n*
 - The shape of a binary search tree determines the efficiency of its operations

Summary

- An inorder traversal of a binary search tree visits the tree’s nodes in sorted search-key order
- The *treесort* algorithm efficiently sorts an array by using the binary search tree’s insertion and traversal operations

Summary

- Saving a binary search tree to a file while performing
 - An inorder traversal enables you to restore the tree as a binary search tree of minimum height
 - A preorder traversal enables you to restore the tree to its original form