

Using Al and IoT to Optimize Smart Farming:

Integrating Robotics with Precision Agriculture

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Introduction/Background

- What is Internet of Things (IoT)?
- What is Smart Farming?
- Why IoT for Smart Farming?
- Importance of Agriculture in the Central Valley
- What is Al and Computer Vision?
- Automation Will Not Replace Jobs



Goal

- Objective:
 - Build a prototype of an IoT and Al-powered robot that reduces human intervention and detects plant diseases in row crops.
- Our Contribution:
 - Exploring TurboPi, an Al-powered robot
 - Designed and implemented a prototype and tested scenarios
 - Learned machine learning using Microsoft resources



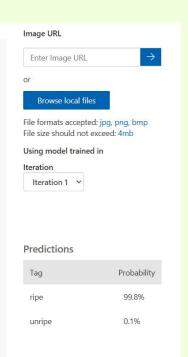
Methodology

- Skill Set:
 - Python, Raspberry Pi, Azure Cloud, TurboPi, OpenCV
- Prototype Phases:
 - Implementing machine learning for image classification using Azure Custom Vision.
 - Using TurboPi, an Al-powered robot with a servomounted camera, to apply computer vision (OpenCV) for color recognition and autonomous navigation through line tracking.



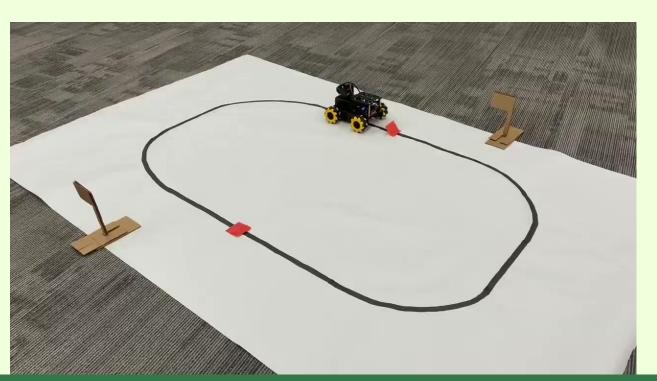
Results

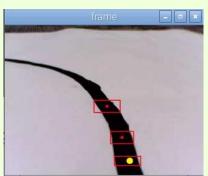






Demo/Results







Future Work

- Short-term Goals:
 - Integrate Machine Learning for Image Classification using Azure Custom Vision with TurboPi
 - Combine line tracking with color detection
 - Image Classification will be trained to detect tomato plants, determining which are unhealthy vs. healthy
- Long-term Goal:
 - Build a fully automated smart farm system with continuous real-time monitoring.



References

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Thank You

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